

5.9 Higher Order Equations and Systems of ODE.

Consider the system:

$$\begin{cases} u_1'(t) = -\frac{1}{2} u_1(t) + u_2(t) \end{cases} \quad (1.1)$$

$$\begin{cases} u_2'(t) = -u_1(t) - \frac{1}{2} u_2(t) \end{cases} \quad (1.2)$$

$$\text{ICs: } u_1(0) = 1, \quad u_2(0) = 1, \quad t \in [0, b]. \quad (1.3)$$

Extension of R-K 4th order to system (1.1) - (1.3).

More general,

$$\begin{cases} u_1'(t) = f_1(t, u_1, u_2), \\ u_2'(t) = f_2(t, u_1, u_2), \end{cases} \quad t \in [0, b]$$

$$u_1(0) = \alpha, \quad u_2(0) = \beta.$$

Discussion on conditions for existence and uniqueness later.

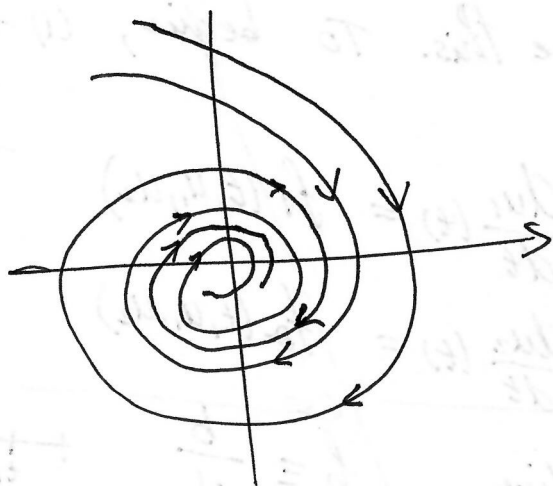
Eigenvalues $r_1 = -\frac{1}{2} + i, r_2 = -\frac{1}{2} - i$ Eigenvectors $\vec{\xi}^{(1)} = \begin{pmatrix} 1 \\ i \end{pmatrix}, \vec{\xi}^{(2)} = \begin{pmatrix} 1 \\ -i \end{pmatrix}$ $\vec{u}(t) = \vec{\xi} e^{rt}$ $(S_{h,1})$

$$\vec{u}(t) = C_1 e^{-t/2} \begin{pmatrix} \cos t \\ -\sin t \end{pmatrix} + C_2 e^{-t/2} \begin{pmatrix} \sin t \\ \cos t \end{pmatrix}$$

$$\begin{pmatrix} 1 \\ 1 \end{pmatrix} = \vec{u}(0) = C_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + C_2 \begin{pmatrix} 0 \\ 1 \end{pmatrix} \Rightarrow \begin{matrix} C_1 = 1 \\ C_2 = 1 \end{matrix}$$

$$\vec{u}(t) = e^{-t/2} \begin{pmatrix} \cos t \\ -\sin t \end{pmatrix} + e^{-t/2} \begin{pmatrix} \sin t \\ \cos t \end{pmatrix}$$

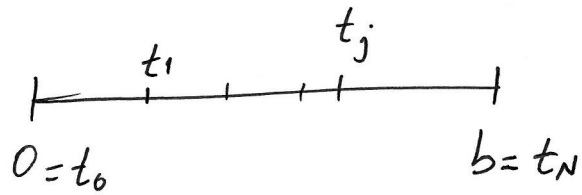
Phase portrait:



$$\vec{u}'(t) = A \vec{u}(t)$$

$$r \vec{\xi} e^{rt} = (A \vec{\xi}) e^{rt} \Rightarrow A \vec{\xi} = r \vec{\xi}$$

$$\begin{pmatrix} -1/2 & 1 \\ -1 & -1/2 \end{pmatrix} \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} = r \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix}$$



$$h = \frac{b-a}{N}$$

$$t_j = a + jh, \quad w_{ij} = \mathcal{U}_i(t_j), \quad \begin{matrix} i=1,2 \\ j=1,2,\dots,N \end{matrix}$$

$$j=0,\dots,N.$$

$$w_{1,0} = \alpha, \quad w_{2,0} = \beta$$

R-K 4th order:

$$\begin{cases} w_{1,j+1} = w_{1,j} + \frac{1}{6} [K_{1,1} + 2K_{2,1} + 2K_{3,1} + K_{4,1}] \\ w_{2,j+1} = w_{2,j} + \frac{1}{6} [K_{1,2} + 2K_{2,2} + 2K_{3,2} + K_{4,2}] \\ w_{1,0} = \alpha, \quad w_{2,0} = \beta \end{cases} \quad j=0,1,2,\dots,N-1.$$

Where

$$K_{1,i} = hf_i(t_j, w_{1,j}, w_{2,j}), \quad i=1,2$$

$$K_{2,i} = hf_i\left(t_j + \frac{h}{2}, w_{1,j} + \frac{1}{2}K_{1,1}, w_{2,j} + \frac{1}{2}K_{1,2}\right)$$

$$K_{3,i} = hf_i\left(t_j + \frac{h}{2}, w_{1,j} + \frac{1}{2}K_{2,1}, w_{2,j} + \frac{1}{2}K_{2,2}\right)$$

$$K_{4,i} = hf_i(t_j + h, w_{1,j} + K_{3,1}, w_{2,j} + K_{3,2})$$

$$i=1,2$$

In our example,

$$\begin{cases} f_1(t, u_1, u_2) = -\frac{1}{2}u_1 + u_2 \\ f_2(t, u_1, u_2) = -u_1 - \frac{1}{2}u_2 \end{cases}$$

$$f_i(t_j, w_{1,j}, w_{2,j}) \approx f_i(t_j, u_1(t_j), u_2(t_j)), \quad i=1,2$$

Then,

$$K_{1,1} = h f_1(t_j, w_{1,j}, w_{2,j}) = h \left[-\frac{1}{2}w_{1,j} + w_{2,j} \right]$$

$$K_{1,2} = h f_2(t_j, w_{1,j}, w_{2,j}) = h \left[-w_{1,j} - \frac{1}{2}w_{2,j} \right]$$

$$K_{2,1} = h f_1\left(t_j + \frac{h}{2}, w_{1,j} + \frac{1}{2}K_{1,1}, w_{2,j} + \frac{1}{2}K_{1,2}\right) = h \left[-\frac{1}{2}\left(w_{1,j} + \frac{1}{2}K_{1,1}\right) + w_{2,j} + \frac{1}{2}K_{1,2} \right]$$

$$\begin{aligned} K_{2,2} &= h f_2\left(t_j + \frac{h}{2}, w_{1,j} + \frac{1}{2}K_{1,1}, w_{2,j} + \frac{1}{2}K_{1,2}\right) = \\ &= h \left[-\left(w_{1,j} + \frac{1}{2}K_{1,1}\right) - \frac{1}{2}\left(w_{2,j} + \frac{1}{2}K_{1,2}\right) \right] \end{aligned}$$

etc. . . .

For more general definition review pp. 315-317. ~~Leve~~ B.F.

Existence and Uniqueness thm.

A m th-order system has the form:

$$\frac{du_1}{dt}(t) = f_1(t, u_1, u_2, \dots, u_m) \quad (3)$$

$$\frac{du_m}{dt}(t) = f_m(t, u_1, u_2, \dots, u_m), \quad a \leq t \leq b$$

IC's are $u_1(a) = \alpha_1, \dots, u_m(a) = \alpha_m \quad (4)$

Def - (Lipschitz cond.)

$$f(t, y_1, \dots, y_m) \text{ defined on } D = \left\{ (t, u_1, \dots, u_m) \mid a \leq t \leq b, -\infty \leq u_i \leq \infty, i=1,2,\dots,m \right\}$$

is said to satisfy a Lipschitz cond. on D in the variables $u_1, \dots, u_m$, if there is $L > 0$ s.t.

$$|f(t, u_1, \dots, u_m) - f(t, z_1, \dots, z_m)| \leq L \sum_{j=1}^m |u_j - z_j| = \|\vec{u} - \vec{z}\|_1$$

It might be any other norm.

for all pair $(t, u_1, \dots, u_m)$ and $(t, z_1, \dots, z_m) \in D$.

Proposition - $f: D \subset \mathbb{R}^{m+1} \rightarrow \mathbb{R}$
 - f and $\frac{\partial f}{\partial u_i}$ are conts on D , $i=1,2,\dots,m$

$$- \left| \frac{\partial f}{\partial u_i}(t, u_1, \dots, u_m) \right| \leq L \quad i=1,2,\dots,m$$

for all $(t, u_1, \dots, u_m) \in D$

Then

f satisfies Lipschitz cond on D with Lipschitz constant L .

Thm 5.17

- $f_i(t, u_1, \dots, u_m)$ are conts on D . $i=1,2,\dots,m$

- f_i satisfy a Lipschitz cond. on D in $u_1, u_2, \dots, u_m$

then, the IVP (3)-(4) has a unique soln.

$$u_1(t), \dots, u_m(t), \quad \text{for } a \leq t \leq b.$$

For our example in 2-D.

$$f_1(t, u_1, u_2) = -\frac{1}{2}u_1 + u_2, \quad D = \{(t, u_1, u_2) \mid 0 \leq t \leq b, -\infty < u_i < \infty\}$$

$$f_2(t, u_1, u_2) = -u_1 - \frac{1}{2}u_2,$$

$$\frac{\partial f_1}{\partial u_1} = -\frac{1}{2}, \quad \frac{\partial f_1}{\partial u_2} = 1, \quad \frac{\partial f_2}{\partial u_1} = -1, \quad \frac{\partial f_2}{\partial u_2} = -\frac{1}{2}$$

$$\left| \frac{\partial f_1}{\partial u_i} \right| \leq 1 = L_1, \quad i=1,2$$

$$\left| \frac{\partial f_2}{\partial u_i} \right| \leq 1 = L_2, \quad i=1,2.$$

f_1, f_2 satisfy Lipschitz cond^{in u_1, u_2} and are conts on D . $\Rightarrow$ There is a unique soln on $[0,1]$.

5.9.13

Higher order IVP $\left\{ \begin{array}{l} y^{(m)}(t) = f(t, y, y', \dots, y^{(m-1)}) \\ y(a) = \alpha_1, y'(a) = \alpha_2, \dots, y^{(m-1)}(a) = \alpha_m \end{array} \right., \quad a \leq t \leq b$ It can be written as an ODE syst. or DVP

$$\begin{cases} u_1 = y \\ u_2 = y' \\ \vdots \\ u_m = y^{(m-1)} \end{cases} \Rightarrow \begin{cases} u_1' = u_2 \\ u_2' = u_3 \\ \vdots \\ u_{m-1}' = u_m \\ u_m' = y^{(m)} = f(t, y, y', \dots, y^{(m-1)}) \end{cases}$$

Example 2 Consider the second-order initial-value problem

$$y'' - 2y' + 2y = e^{2t} \sin t, \quad \text{for } 0 \leq t \leq 1, \quad \text{with } y(0) = -0.4, \quad y'(0) = -0.6.$$

Let $u_1(t) = y(t)$ and $u_2(t) = y'(t)$. This transforms the equation into the system

$$\boxed{u_1'(t) = u_2(t)}, \quad \boxed{u_2'(t) = e^{2t} \sin t - 2u_1(t) + 2u_2(t)},$$

with initial conditions $f_1(t, u_1, u_2)$ $f_2(t, u_1, u_2)$

$$u_1(0) = -0.4, \quad u_2(0) = -0.6.$$

The Runge-Kutta fourth-order method will be used to approximate the solution to this problem using $h = 0.1$. The initial conditions give $w_{1,0} = -0.4$ and $w_{2,0} = -0.6$. Eqs. (5.48) through (5.51) with $j = 0$ give

$$k_{1,1} = hf_1(t_0, w_{1,0}, w_{2,0}) = hw_{2,0} = -0.06,$$

$$k_{1,2} = hf_2(t_0, w_{1,0}, w_{2,0}) = h[e^{2t_0} \sin t_0 - 2w_{1,0} + 2w_{2,0}] = -0.04,$$

$$k_{2,1} = hf_1\left(t_0 + \frac{h}{2}, w_{1,0} + \frac{1}{2}k_{1,1}, w_{2,0} + \frac{1}{2}k_{1,2}\right) = h[w_{2,0} + \frac{1}{2}k_{1,2}] = -0.062,$$

$$\begin{aligned} k_{2,2} &= hf_2\left(t_0 + \frac{h}{2}, w_{1,0} + \frac{1}{2}k_{1,1}, w_{2,0} + \frac{1}{2}k_{1,2}\right) \\ &= h\left[e^{2(t_0+0.05)} \sin(t_0+0.05) - 2\left(w_{1,0} + \frac{1}{2}k_{1,1}\right) + 2\left(w_{2,0} + \frac{1}{2}k_{1,2}\right)\right] \\ &= -0.03247644757, \end{aligned}$$

$$k_{3,1} = h\left[w_{2,0} + \frac{1}{2}k_{2,2}\right] = -0.06162832238,$$

$$k_{3,2} = h\left[e^{2(t_0+0.05)} \sin(t_0+0.05) - 2\left(w_{1,0} + \frac{1}{2}k_{2,1}\right) + 2\left(w_{2,0} + \frac{1}{2}k_{2,2}\right)\right]$$

$$= f(t, u_1, u_2, \dots, u_m)$$

IC's:

$$u_1(a) = \alpha_1$$

$$u_2(a) = \alpha_2$$

$$\vdots$$

$$u_m(a) = \alpha_m$$

$$= -0.03152409237,$$

$$k_{4,1} = h [w_{2,0} + k_{3,2}] = -0.06315240924,$$

and

$$k_{4,2} = h [e^{2(t_0+0.1)} \sin(t_0 + 0.1) - 2(w_{1,0} + k_{3,1}) + 2(w_{2,0} + k_{3,2})] = -0.02178637298.$$

So

$$w_{1,1} = w_{1,0} + \frac{1}{6}(k_{1,1} + 2k_{2,1} + 2k_{3,1} + k_{4,1}) = -0.4617333423$$

and

$$w_{2,1} = w_{2,0} + \frac{1}{6}(k_{1,2} + 2k_{2,2} + 2k_{3,2} + k_{4,2}) = -0.6316312421.$$

The value $w_{1,1}$ approximates $u_1(0.1) = y(0.1) = 0.2e^{2(0.1)}(\sin 0.1 - 2 \cos 0.1)$, and $w_{2,1}$ approximates $u_2(0.1) = y'(0.1) = 0.2e^{2(0.1)}(4 \sin 0.1 - 3 \cos 0.1)$.

The set of values $w_{1,j}$ and $w_{2,j}$, for $j = 0, 1, \dots, 10$, obtained using the Runge-Kutta method of order four, are presented in Table 5.18 and are compared to the actual values of $u_1(t) = 0.2e^{2t}(\sin t - 2 \cos t)$ and $u_2(t) = u'_1(t) = 0.2e^{2t}(4 \sin t - 3 \cos t)$. ■

5.18

$y(t_j) = u_1(t_j)$	$w_{1,j}$	$y'(t_j) = u_2(t_j)$	$w_{2,j}$	$ y(t_j) - w_{1,j} $	$ y'(t_j) - w_{2,j} $
-0.40000000	-0.40000000	-0.60000000	-0.60000000	0	0
-0.46173297	-0.46173334	-0.6316304	-0.63163124	3.7×10^{-7}	7.75×10^{-7}
-0.52555905	-0.52555988	-0.6401478	-0.64014895	8.3×10^{-7}	1.01×10^{-6}
-0.58860005	-0.58860144	-0.6136630	-0.61366381	1.39×10^{-6}	8.34×10^{-7}
-0.64661028	-0.64661231	-0.5365821	-0.53658203	2.03×10^{-6}	1.79×10^{-7}
-0.69356395	-0.69356666	-0.3887395	-0.38873810	2.71×10^{-6}	5.96×10^{-7}
-0.72114849	-0.72115190	-0.1443834	-0.14438087	3.41×10^{-6}	7.75×10^{-7}
-0.71814890	-0.71815295	0.2289917	0.22899702	4.05×10^{-6}	2.03×10^{-6}
-0.66970677	-0.66971133	0.7719815	0.77199180	4.56×10^{-6}	5.30×10^{-6}
-0.55643814	-0.55644290	1.534764	1.5347815	4.76×10^{-6}	9.54×10^{-6}
-0.35339436	-0.35339886	2.578741	2.5787663	4.50×10^{-6}	1.34×10^{-5}

We can also use Maple from Maple on Higher-order equations. The following is the Maple